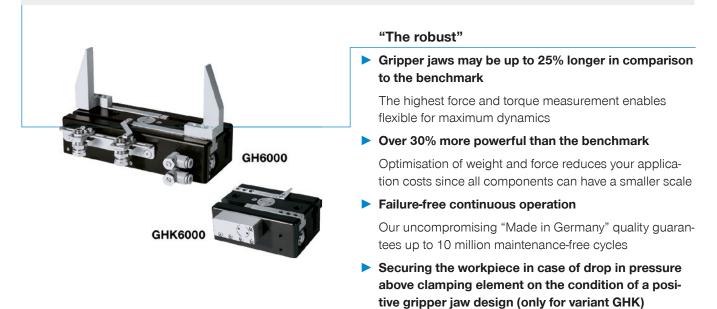
### 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000

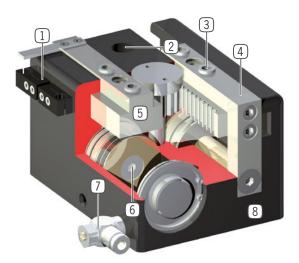
### PRODUCT ADVANTAGES



### SERIES CHARACTERISTICS

Installation size / Variant					
	GH60XX	GHK60XX			
Position maintenance by means of clamp- ing element		•			
10 million maintenance-free cycles (max.)	•	•			
+ 💭 Inductive sensor	•	•			
Hagnetic field sensor	•	•			
IP 40 IP40	•	•			

### BENEFITS IN DETAIL



#### 1 Mounting block

- mounting for inductive proximity switch

### 2 Mounting and positioning

- mounting possible from several sides for versatile positioning
- 3 Removable centering sleeves
  - quick and economical positioning of the gripper fingers

#### (4) Gripper jaw

- individual gripper finger mounting

### 5 Precise long T-Slot guides

- high forces and moments capacity

#### 6 Drive

- two double-acting pneumatic cylinders
- synchronized by gearwheel

### 7 Energy supply

- possible from several sides
- CAUTION: always operate long stroke gripper with supplied exhaust air flow control valve (speed regulation)

#### 8 Robust, lightweight housing

- Hard-coated aluminum alloy

### TECHNICAL DATA

	Stroke per jaw	Gripping force	Weight	IP class
Installation size	[mm]	[N]	[kg]	
GH6000	20 - 80	120 - 155	0,33 - 0,76	IP40
GH6100	20 - 80	340 - 530	1 - 2,3	IP40
GH6200	20 - 150	850 - 1400	2,5 - 7,5	IP40
GH6300	60 - 150	1520 - 2270	7,3 - 12	IP40
GH6400	60 - 200	2600 - 3400	11 - 23	IP40

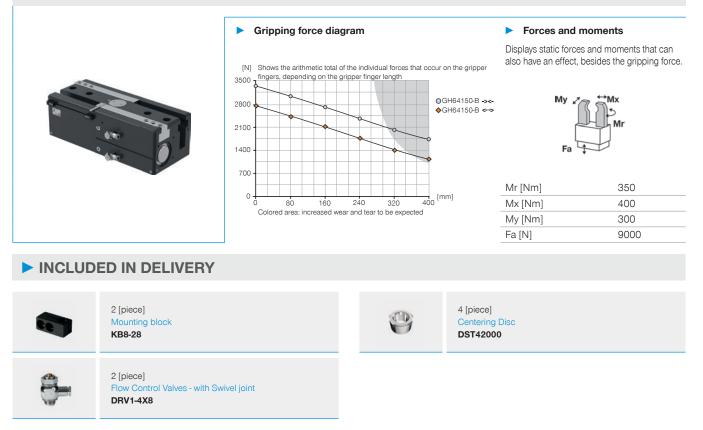
### **FURTHER INFORMATION IS AVAILABLE ONLINE**



All information just a click away at: www.zimmer-group.com. Find data, illustrations, 3D models and operating instructions for your installation size using the order number for your desired product. Quick, clear and always up-to-date.

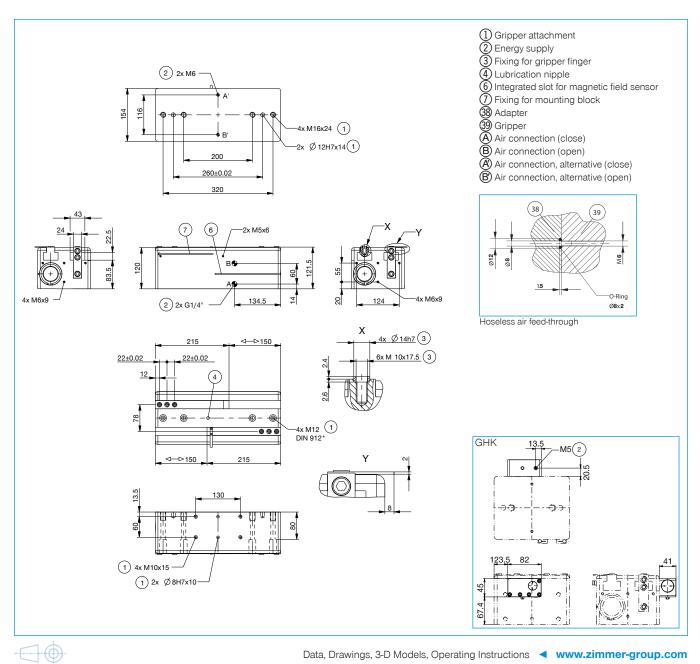
# 2-JAW PARALLEL GRIPPERS WITH LONG STROKE INSTALLATION SIZE GH64150

### PRODUCT SPECIFICATIONS



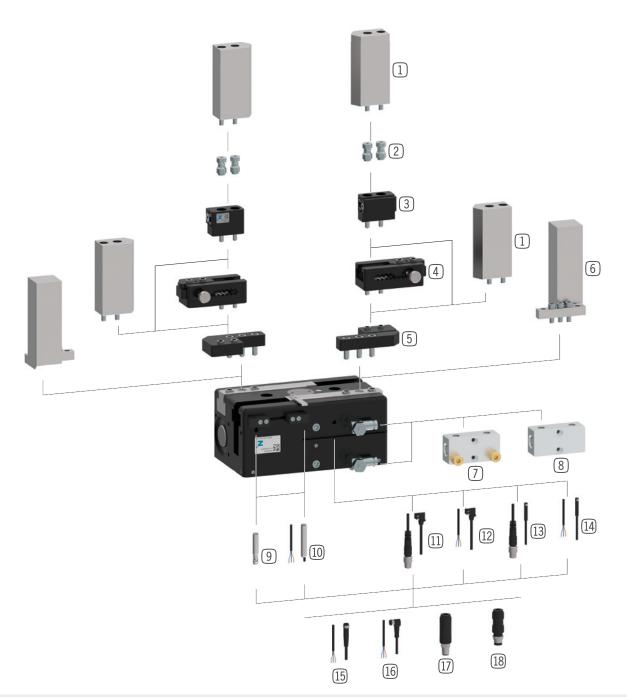
YOU CAN FIND RECOMMENDED ACCESSORIES ON THE FOLLOWING PAGES

	Technical data	
Order no.	GH64150-B	GHK64150
Stroke per jaw [mm]	150	150
Gripping force in closing [N]	3300	3300
Gripping force in opening [N]	2780	2780
Closing time [s]	1	1
Opening time [s]	1	1
Dead weight of mounted gripper finger max. [kg]	6	6
Length of the gripper fingers max. [mm]	400	400
Repetition accuracy +/- [mm]	0.05	0.05
Operating pressure min. [bar]	3	3
Operating pressure max. [bar]	8	8
Nominal operating pressure [bar]	6	6
Operating temperature min. [°C]	+5	+5
Operating temperature max. [°C]	+80	+80
Air volume per cycle [cm <sup>3</sup> ]	1775	1775
Protection to IEC 60529	IP40	IP40
Weight [kg]	18	19



# **2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 - ACCESSORIES**

### ACCESORIES



### RECOMMENDED ACCESSORIES GH6000

Pos.	Order no.	Accessories	Pos.	Order no.	Accessories
1	UB5004AL	* Universal jaw aluminium	9	NJ6.5-E2S	** Inductive proximity switch - Connector M8
1	UB5004ST	* Universal jaw steel	10	NJ6.5-E2-01	** Inductive proximity switch - Cable 5 m
2	WB5004L	* Changeable jaw, loose-part-set	11	MFS01-S-KHC-P1-PNP	Magnetic field sensor angled, cable 0.3 m - M8 connector
3	WB5004F	* Changeable jaw, fix-part	12	MFS01-K-KHC-P1-PNP	Magnetic field sensor angled, cable 5 m
4	EB5004ST	* Steel adjustment jaw	13	MFS02-S-KHC-P1-PNP	Magnetic field sensor straight, cable 0.3 m - M8 connector
4	EB5004AL	* Aluminum adjustment jaw	14	MFS02-K-KHC-P1-PNP	Magnetic field sensor straight, cable 5 m
5	APGH6000	Adapter plate	15	KAG500	Plug-in connector Straight Cable 5m - Socket M8 (female
6	UB6000-B	Universal jaw set aluminium	16	KAW500	Plug-in connector Angled Cable 5m - Socket M8 (female)
7	DSV1-8E	Pressure safety valve with quick exhaust	17	S8-G-3	Plug-in connector customizable Straight - Connector M8
8	DSV1-8	Pressure safety valve	18	S12-G-3	Plug-in connector customizable Straight - Connector M12
*in c	onjunction with pos. (5)		* * nc	ot with GH6020	

2

www.zimmer-group.com > Data, Drawings, 3-D Models, Operating Instructions

### RECOMMENDED ACCESSORIES GH6100

Pos.	Order no.	Accessories
1	UB5006AL	<ul> <li>Universal jaw aluminium</li> </ul>
1	UB5006ST	<ul> <li>Universal jaw steel</li> </ul>
2	WB5006L	<ul> <li>Changeable jaw, loose-part-set</li> </ul>
3	WB5006F	<ul> <li>Changeable jaw, fix-part</li> </ul>
4	EB5006ST	<ul> <li>Steel adjustment jaw</li> </ul>
4	EB5006AL	<ul> <li>Aluminum adjustment jaw</li> </ul>
5	APGH6100	Adapter plate
6	UB6100-B	Universal jaw set aluminium
7	DSV1-8E	Pressure safety valve with quick exhaust
8	DSV1-8	Pressure safety valve

\* in conjunction with pos.  $\overline{\mathbf{5}}$ 

### RECOMMENDED ACCESSORIES GH6200

Pos.	Order no.	Accessories
1	UB5008AL	Universal jaw aluminium
1	UB5008ST	* Universal jaw steel
2	WB5008L	<ul> <li>Changeable jaw, loose-part-set</li> </ul>
3	WB5008F	<ul> <li>Changeable jaw, fix-part</li> </ul>
4	EB5008ST	* Steel adjustment jaw
4	EB5008AL	<ul> <li>Aluminum adjustment jaw</li> </ul>
5	APGH6200	Adapter plate
6	UB6200-B	Universal jaw set aluminium
7	DSV1-8E	Pressure safety valve with quick exhaust
8	DSV1-8	Pressure safety valve

\*in conjunction with pos. (5)

### RECOMMENDED ACCESSORIES GH6300

Pos.	Order no.	Accessories
(1)	UB5010ST	<ul> <li>Universal jaw steel</li> </ul>
1	UB5010AL	<ul> <li>Universal jaw aluminium</li> </ul>
2	WB5010L	<ul> <li>Changeable jaw, loose-part-set</li> </ul>
3	WB5010F	<ul> <li>Changeable jaw, fix-part</li> </ul>
4	EB5010ST	* Steel adjustment jaw
4	EB5010AL	<ul> <li>Aluminum adjustment jaw</li> </ul>
5	APGH6300	Adapter plate
7	DSV1-8E	Pressure safety valve with quick exhaust
8	DSV1-8	Pressure safety valve
9	NJ8-E2S	Inductive proximity switch - Connector M8

\*in conjunction with pos. (5)

### RECOMMENDED ACCESSORIES GH6400

Pos.	Order no.	Accessories
1	UB5016ST *	Universal jaw steel
1	UB5016AL *	Universal jaw aluminium
2	WB5016L *	Changeable jaw, loose-part-set
3	WB5016F *	Changeable jaw, fix-part
4	EB5016ST *	Steel adjustment jaw
4	EB5016AL *	Aluminum adjustment jaw
5	APGH6400	Adapter plate
7	DSV1-8E	Pressure safety valve with quick exhaust
8	DSV1-8	Pressure safety valve
9	NJ8-E2S	Inductive proximity switch - Connector M8

\*in conjunction with pos. 5

Pos.	Order no.	Accessories
9	NJ8-E2S *	<ul> <li>Inductive proximity switch - Connector M8</li> </ul>
10	NJ8-E2 *	* Inductive proximity switch - Cable 5 m
11	MFS01-S-KHC-P1-PNP	Magnetic field sensor angled, cable 0.3 m - M8 connector
12	MFS01-K-KHC-P1-PNP	Magnetic field sensor angled, cable 5 m
13	MFS02-S-KHC-P1-PNP	Magnetic field sensor straight, cable 0.3 m - M8 connector
14	MFS02-K-KHC-P1-PNP	Magnetic field sensor straight, cable 5 m
15	KAG500	Plug-in connector Straight Cable 5m - Socket M8 (female)
16	KAW500	Plug-in connector Angled Cable 5m - Socket M8 (female)
17	S8-G-3	Plug-in connector customizable Straight - Connector M8
18	S12-G-3	Plug-in connector customizable Straight - Connector M12
* * no	t with GH6120	

Pos.	Order no.		Accessories
9	NJ8-E2S	**	Inductive proximity switch - Connector M8
10	NJ8-E2	**	Inductive proximity switch - Cable 5 m
11	MFS01-S-KHC-P1-PNP		Magnetic field sensor angled, cable 0.3 m - M8 connector
12	MFS01-K-KHC-P1-PNP		Magnetic field sensor angled, cable 5 m
13	MFS02-S-KHC-P1-PNP		Magnetic field sensor straight, cable 0.3 m - M8 connector
14	MFS02-K-KHC-P1-PNP		Magnetic field sensor straight, cable 5 m
15	KAG500		Plug-in connector Straight Cable 5m - Socket M8 (female)
16	KAW500		Plug-in connector Angled Cable 5m - Socket M8 (female)
17)	S8-G-3		Plug-in connector customizable Straight - Connector M8
18	S12-G-3		Plug-in connector customizable Straight - Connector M12
* * no	t with GH6220		

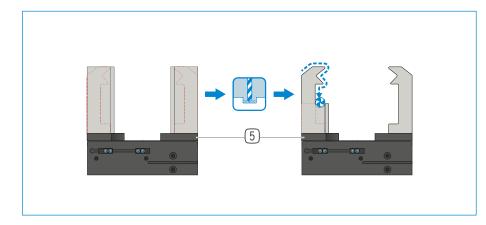
Pos. Order no. Accessories NJ8-E2 10 Inductive proximity switch - Cable 5 m 11 MFS01-S-KHC-P1-PNP Magnetic field sensor angled, cable 0.3 m - M8 connector 12 MFS01-K-KHC-P1-PNP Magnetic field sensor angled, cable 5 m 13 MFS02-S-KHC-P1-PNP Magnetic field sensor straight, cable 0.3 m - M8 connector 14 MFS02-K-KHC-P1-PNP Magnetic field sensor straight, cable 5 m 15 KAG500 Plug-in connector Straight Cable 5m - Socket M8 (female) (16) KAW500 Plug-in connector Angled Cable 5m - Socket M8 (female) 17 S8-G-3 Plug-in connector customizable Straight - Connector M8 18 S12-G-3 Plug-in connector customizable Straight - Connector M12

Pos.	Order no.	Accessories
10	NJ8-E2	Inductive proximity switch - Cable 5 m
11	MFS01-S-KHC-P1-PNP	Magnetic field sensor angled, cable 0.3 m - M8 connector
12	MFS01-K-KHC-P1-PNP	Magnetic field sensor angled, cable 5 m
13	MFS02-S-KHC-P1-PNP	Magnetic field sensor straight, cable 0.3 m - M8 connector
14	MFS02-K-KHC-P1-PNP	Magnetic field sensor straight, cable 5 m
15	KAG500	Plug-in connector Straight Cable 5m - Socket M8 (female)
16	KAW500	Plug-in connector Angled Cable 5m - Socket M8 (female)
17)	S8-G-3	Plug-in connector customizable Straight - Connector M8
18	S12-G-3	Plug-in connector customizable Straight - Connector M12
	1	

### 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 FUNCTIONAL DESCRIPTION



### **GRIPPING COMPONENTS**



### Universal jaws – UB5000

Can be used immediately or for individual reprocessing

The gripper blanks are available in aluminum (AL) and steel (ST) versions and are installed directly on the gripper using the screws in the scope of delivery. The fits for the centering sleeves are already in place for this purpose. One universal jaw is required for each gripper jaw.

# 

### Adjustment jaws - EB5000

For tool-free adaptation of the gripper range

By manually activating the locking mechanism, which is pre-tensioned by a spring, the adjustment jaw can be moved within a grid of detent notches that has a number scale. Depending on the forces and torques that apply, the adjustment jaws are available in aluminum (AL) and steel (ST) versions. One adjustment jaw is required for each gripper jaw.



Enable fast change of individual gripper fingers

For each gripper jaw, a fixed part and at least one loose part set is needed, depending on the number of gripper fingers to be changed. Manual locking via the Torx wrench included in the scope of delivery of the fixed part can take place from two sides.

### THE GRIPPING COMPONENTS CAN BE COMBINED!

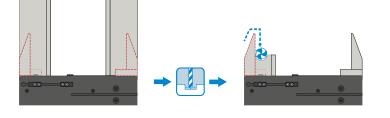
 $(\mathbf{I})$ 

(5)

The gripping components listed above can be combined with each other. For connection to the gripper, the adapter plate (5), which is included in the recommended accessories for the gripper, is required.



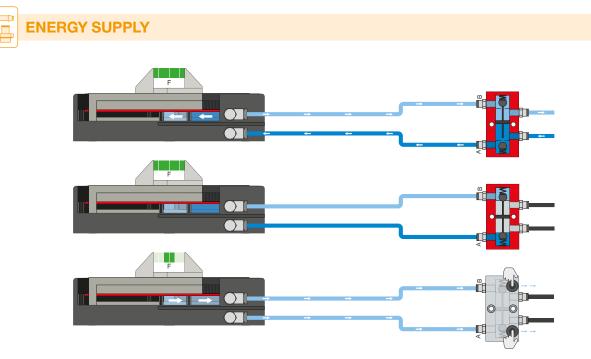
### **GRIPPING COMPONENTS**



#### Universal jaws - UB6000-B

Can be used immediately or for individual reprocessing

The gripper blanks are available in an aluminum (AL) version and are installed directly on the gripper using the screws in the scope of delivery. The fits for the centering sleeves are already in place for this purpose. One universal jaw set is required for each gripper.



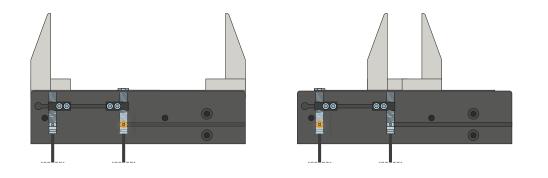
#### Pressure safety valve – DSV

Ensures safe retention of force and position if the system pressure drops

The integrated double check valve, which can be unlocked, retains the system pressure of the gripper in case of EMERGENCY STOP. To ensure the function, the valve must be installed as close to the gripper's air connection as possible. In variant E, two pushbuttons are installed that allow for controlled bleeding of the gripper.

### 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 FUNCTIONAL DESCRIPTION

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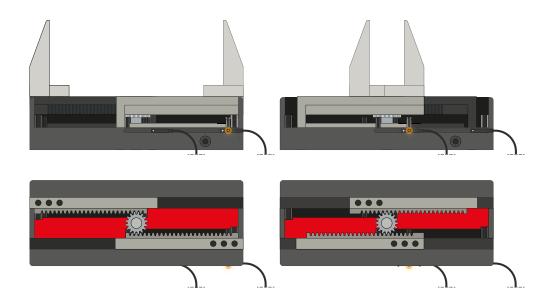


### Inductive sensors – NJ

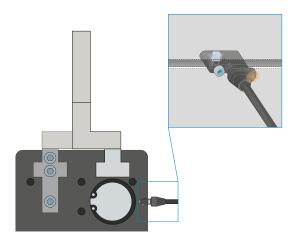
The mounting block is aligned to the cam switch, and the sensor is guided into the mounting block until the required switching distance to the cam switch is reached. Fine adjustment can be made by moving the mounting block again. The sensors are available in versions with 5 m cables with exposed leads and 0,3 m cable with connector, as well as with direct plug orientation.

### SENSORS

### MFS02



MFS01



### 1-point magnetic field sensors - MFS

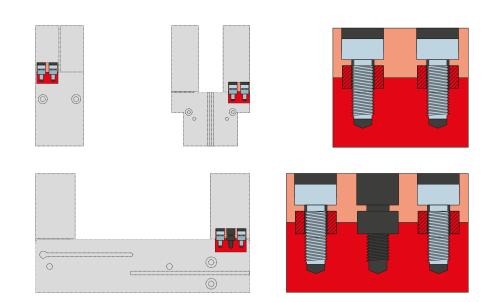
For non-contact sensing of the piston position

These sensors are installed in the C-groove of the gripper and detect the magnet attached to the piston of the gripper. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFS02, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFS01 is taller, but has a cable outlet that is offset at an angle of 90°. The variants are available in versions with 5 m cables with exposed leads and 0,3 m cable with connector.

# 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 FUNCTIONAL DESCRIPTION



### **CONNECTIONS / OTHER**



### **Centering sleeves**

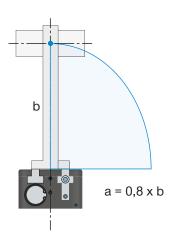
For defined position measurement of the gripper fingers

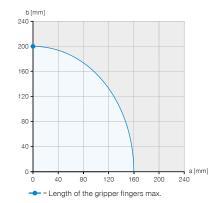
The centering sleeves are inserted into the fits of the gripper jaws to define the position of the gripper fingers. The centering sleeves are comparable to a pin connection.

### 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 GRIPPER FINGER LENGTH

### MAXIMUM GRIPPER FINGER LENGTH

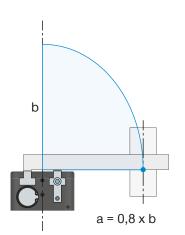
The examples show the maximum horizontal (a) and vertical (b) gripper finger length for a GH6140-B, illustrated by the blue area. The approach is identical for all other grippers of this series. The projection (a) is determined by multiplying the max. length of the gripper fingers (b) by 0.8. For the max. length of the gripper fingers, refer to the data sheet of the respective gripper.

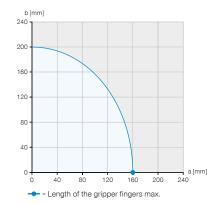




### Example 1

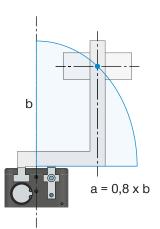
Vertical force application point a = 0 mm b = 200 mm

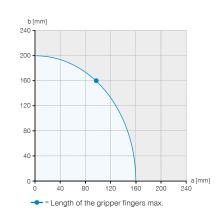




### Example 2

Horizontal force application point a = 160 mm b = 0 mm

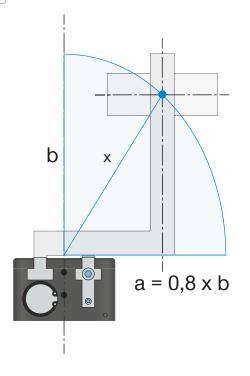




### Example 3

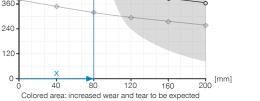
Maximum permissible projection a = 96 mm b = 160 mm

### **GRIPPING FORCE AS A FUNCTION OF GRIPPER FINGER LENGTH**



#### Gripping force diagram

[N] Shows the arithmetic total of the individual forces that occur on the gripper fingers, depending on the gripper finger length 480 480 480 GH6140-B > GH6140-B -> GH6140-B -> GH6140-B -> CH6140-B -



#### **Example 4**

Resulting gripper finger length for determining the gripping force a = 55 mm

b = 58 mm

 $x = \sqrt{55^2 + 58^2} = 80 => 435 N$ 

The specified maximum gripper jaw length in the gripper technical data refers to a vertical (b) alignment of the gripper jaws. With a horizontal (a) overhang, the maximum gripper jaw length is reduced accordingly. The table shows the maximum gripper jaw lengths of the individual sizes.

If the required gripper jaw length lies within the tinted area of the gripping force diagram, increased wear must be expected - possibly reduce pressure.

### TECHNICAL DATA

	Dead weight of mounted gripper finger max.	Length of the gripper fingers max. vertical (b)	Length of the gripper fingers max. horizontal (a)
Installation size	[kg]	[mm]	[mm]
GH6000	0.3	150	120
GH6100	1	200	160
GH6200	2.5	250	200
GH6300	3.5	300	240
GH6400	6	400	320

### 2-JAW PARALLEL GRIPPERS WITH LONG STROKE SERIES GH6000 GRIPPER FINGER WEIGHT

### DEAD WEIGHT OF MOUNTED GRIPPER FINGER

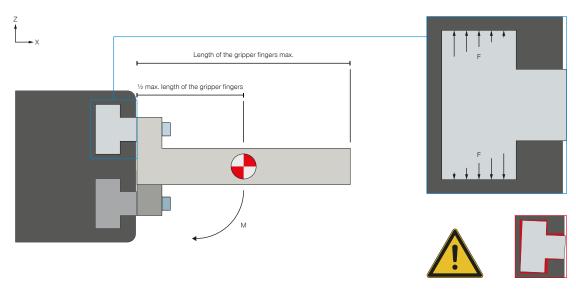
The 6000 gripper series is equipped with a T-slot guide. For the gripper finger design, we take two different cases into account.

### 1. Static

The workpiece is gripped or gripper without workpiece and the opening or closing stroke of the gripper is not carried out. This is where the schematic diagram of the forces and torques included in the data sheet becomes important.

### 2. Load on the guide when opening and closing the gripper

In the gripping direction, Mx, high torques can be transferred by the long T-slot guides. The shorter guide ratio in the My direction results in limitations with respect to the gripper finger lengths and their weights. The effect of the resulting torque is that the gripper jaw gets twisted in the guide when it is overloaded and runs along the edge. In the guides, increased wear is to be expected as a result of this line load. This may also lead to chatter during the movement and, in extreme cases, to the gripper getting jammed. As a countermeasure, a maximum gripper finger weight and length have been recorded in the data sheet. The maximum permitted torque that is allowed to act upon the guide when opening and closing the gripper is calculated using the specified maximum gripper finger weight.



Mmax= 1/2 max. length of the gripper fingers \* max. dead weight, mounted gripper finger \* g

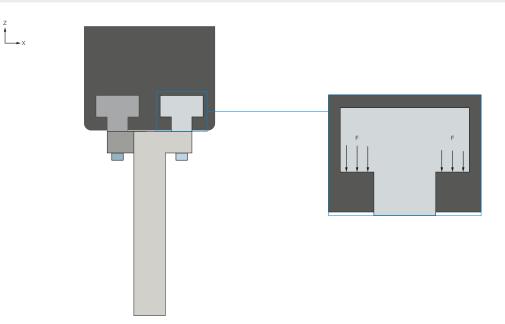
### Horizontal alignment

To calculate the torque, the center of force is placed at the halfway point of the maximum gripper finger length and multiplied by the maximum gripper finger weight.

### Example

My Fa	
Mr [Nm]	70
Mx [Nm]	100
My [Nm]	60
Fa [N]	1500

### DEAD WEIGHT OF MOUNTED GRIPPER FINGER



### Vertical alignment

If the gripper fingers are aligned vertically during the gripping process, the gripper finger weight is negligible. The maximum permitted torques are typically not reached in this gripping situation. In this case, an overload can only be caused by designs in which the gripper fingers jut out a great deal.