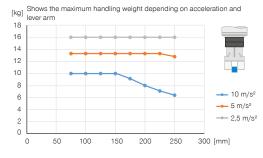
# **MATCH - ROBOT MODULE**

# LWR50F-07-01-A

### **▶ PRODUCT SPECIFICATIONS**



Vertical design with centered holding force



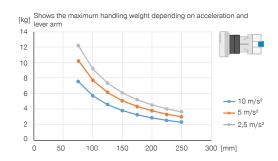
#### Forces and moments

Shows static forces and moments



| Mr [Nm] | 20  |
|---------|-----|
| My [Nm] | 40  |
| Fa [N]  | 500 |

#### Horizontal design with centered holding force



### ► RECOMMENDED ACCESSORIES



## **GRIPPING COMPONENTS**



LWR50L-03-00002-A



# **CONNECTIONS / OTHER**



WVM7 Angled Fittings - Quick Connect Style



LWR50L-23-00006-A Match - Grippers



ZUB123084 Strain relief

|   | ► Technical data     |
|---|----------------------|
| Order no.                                 | LWR50F-07-01-A       |
| Suitable for robot type                   | HANWHA HCR-3/-5/-12* |
| Control                                   | Digital I/O          |
| IO logic                                  | NPN                  |
| Connecting flange according EN ISO 9409-1 | TK 50                |
| Handling weight max. [kg]                 | 25                   |
| Connecting cable                          | Socket, M8, 8-pole   |
| Locking stroke [mm]                       | 1                    |
| Electrical energy transfer                | integrated           |
| Pneumatic energy transfer                 | integrated           |
| Tightening force [N]                      | 50                   |
| Release force [N]                         | 0                    |
| Repetition accuracy in X, Y [mm]          | 0.05                 |
| Repetition accuracy in Z [mm]             | 0.05                 |
| Offset at coupling max. in X,Y [mm]       | 1.0                  |
| Operating temperature [°C]                | 5 +60                |
| Service life in cycles                    | 100,000              |
| Protection to IEC 60529                   | IP40                 |
| Weight [kg]                               | 0.28                 |

<sup>\*</sup>suitable for all HCR-3, HCR-5 and HCR-12 as of hardware revision Q1/2020

